

NAG Toolbox for MATLAB

f07hs

1 Purpose

f07hs solves a complex Hermitian positive-definite band system of linear equations with multiple right-hand sides,

$$AX = B,$$

where A has been factorized by f07hr.

2 Syntax

```
[b, info] = f07hs(uplo, kd, ab, b, 'n', n, 'nrhs_p', nrhs_p)
```

3 Description

f07hs is used to solve a complex Hermitian positive-definite band system of linear equations $AX = B$, the function must be preceded by a call to f07hr which computes the Cholesky factorization of A . The solution X is computed by forward and backward substitution.

If **uplo** = 'U', $A = U^H U$, where U is upper triangular; the solution X is computed by solving $U^H Y = B$ and then $UX = Y$.

If **uplo** = 'L', $A = LL^H$, where L is lower triangular; the solution X is computed by solving $LY = B$ and then $L^H X = Y$.

4 References

Golub G H and Van Loan C F 1996 *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

5.1 Compulsory Input Parameters

1: **uplo** – string

Indicates how A has been factorized.

uplo = 'U'

$A = U^H U$, where U is upper triangular.

uplo = 'L'

$A = LL^H$, where L is lower triangular.

Constraint: **uplo** = 'U' or 'L'.

2: **kd** – int32 scalar

k_d , the number of superdiagonals or subdiagonals of the matrix A .

Constraint: **kd** ≥ 0 .

3: **ab(ldab,*)** – complex array

The first dimension of the array **ab** must be at least **kd** + 1

The second dimension of the array must be at least $\max(1, \mathbf{n})$

The Cholesky factor of A , as returned by f07hr.

4: **b(ldb,*)** – **complex array**

The first dimension of the array **b** must be at least $\max(1, \mathbf{n})$

The second dimension of the array must be at least $\max(1, \mathbf{nrhs_p})$

The n by r right-hand side matrix B .

5.2 Optional Input Parameters

1: **n** – **int32 scalar**

Default: The second dimension of the array **ab**.

n , the order of the matrix A .

Constraint: $\mathbf{n} \geq 0$.

2: **nrhs_p** – **int32 scalar**

Default: The second dimension of the array **b**.

r , the number of right-hand sides.

Constraint: $\mathbf{nrhs_p} \geq 0$.

5.3 Input Parameters Omitted from the MATLAB Interface

ldab, ldb

5.4 Output Parameters

1: **b(ldb,*)** – **complex array**

The first dimension of the array **b** must be at least $\max(1, \mathbf{n})$

The second dimension of the array must be at least $\max(1, \mathbf{nrhs_p})$

The n by r solution matrix X .

2: **info** – **int32 scalar**

info = 0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

info = $-i$

If **info** = $-i$, parameter i had an illegal value on entry. The parameters are numbered as follows:

1: **uplo**, 2: **n**, 3: **kd**, 4: **nrhs_p**, 5: **ab**, 6: **ldab**, 7: **b**, 8: **ldb**, 9: **info**.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

7 Accuracy

For each right-hand side vector b , the computed solution x is the exact solution of a perturbed system of equations $(A + E)x = b$, where

if **uplo** = 'U', $|E| \leq c(k+1)\epsilon \|U^H\| \|U\|$;
 if **uplo** = 'L', $|E| \leq c(k+1)\epsilon \|L\| \|L^H\|$,

$c(k+1)$ is a modest linear function of $k+1$, and ϵ is the *machine precision*.

If \hat{x} is the true solution, then the computed solution x satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_\infty}{\|x\|_\infty} \leq c(k+1) \text{cond}(A, x) \epsilon$$

where $\text{cond}(A, x) = \| |A^{-1}| |A| |x| \|_\infty / \|x\|_\infty \leq \text{cond}(A) = \| |A^{-1}| |A| \|_\infty \leq \kappa_\infty(A)$. Note that $\text{cond}(A, x)$ can be much smaller than $\text{cond}(A)$.

Forward and backward error bounds can be computed by calling f07hv, and an estimate for $\kappa_\infty(A)$ ($= \kappa_1(A)$) can be obtained by calling f07hu.

8 Further Comments

The total number of real floating-point operations is approximately $16nkr$, assuming $n \gg k$.

This function may be followed by a call to f07hv to refine the solution and return an error estimate.

The real analogue of this function is f07he.

9 Example

```
uplo = 'L';
kd = int32(1);
ab = [complex(9.39, +0), complex(1.69, +0), complex(2.65, +0),
      complex(2.17, +0);
      complex(1.08, +1.73), complex(-0.04, -0.29), complex(-0.33, -2.24),
      complex(0, 0)];
b = [complex(-12.42, +68.42), complex(54.3, -56.56);
      complex(-9.93, +0.88), complex(18.32, +4.76);
      complex(-27.3, -0.01), complex(-4.4, +9.9700000000000001);
      complex(5.31, +23.63), complex(9.43, +1.41)];
[ab, info] = f07hr(uplo, kd, ab);
[bOut, info] = f07hs(uplo, kd, ab, b)
```

```
bOut =
-1.0000 + 8.0000i    5.0000 - 6.0000i
 2.0000 - 3.0000i    2.0000 + 3.0000i
-4.0000 - 5.0000i   -8.0000 + 4.0000i
 7.0000 + 6.0000i   -1.0000 - 7.0000i
info =
      0
```